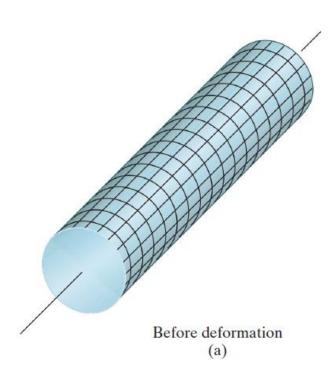
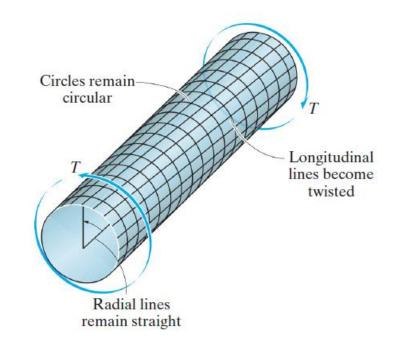
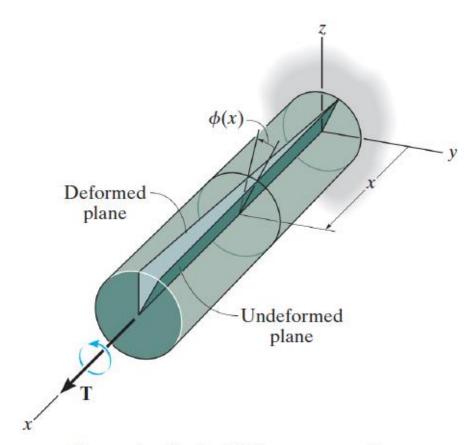


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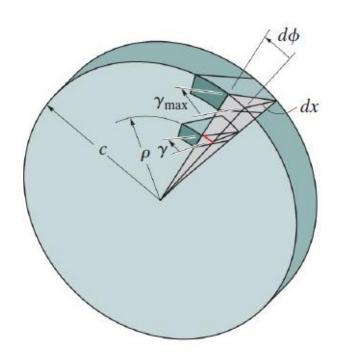




The angle of twist $\phi(x)$ increases as x increases.

(a)

 $\beta \rho d\phi = dx \gamma \qquad \qquad \gamma = \rho \frac{d\phi}{dx}$



The shear strain at points on the cross section increases linearly with ρ , i.e., $\gamma = (\rho/c)\gamma_{\text{max}}$.

$$\gamma = \left(\frac{\rho}{c}\right) \gamma_{\text{max}}$$

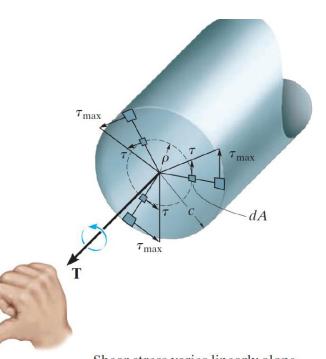
THE TORSION FORMULA

Hooke's law applies, $\tau = G\gamma$

$$\tau_{\rm max} = G\gamma_{\rm max}$$

linear variation in shear strain

$$\tau = \left(\frac{\rho}{c}\right) \tau_{\text{max}}$$



Shear stress varies linearly along each radial line of the cross section.

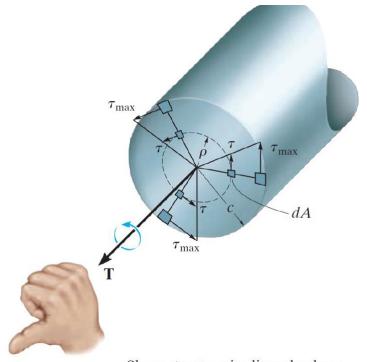
THE TORSION FORMULA

Since each element of area dA, located at ρ , is subjected to a force of $dF = \tau dA$, Fig. 5–3, the torque produced by this force is then $dT = \rho(\tau dA)$. For the entire cross section we have

$$T = \int_{A} \rho(\tau \, dA) = \int_{A} \rho\left(\frac{\rho}{c}\right) \tau_{\text{max}} \, dA$$

However, τ_{max}/c is constant, and so

$$T = \frac{\tau_{\text{max}}}{c} \int_{A} \rho^2 \ dA$$



THE TORSION FORMULA

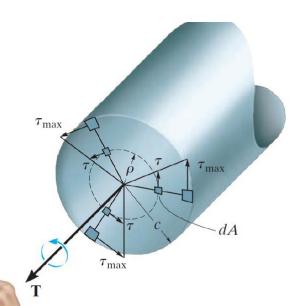
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$$T = \frac{\tau_{\text{max}}}{c} \int_{A} \rho^2 \ dA$$

polar moment of inertia



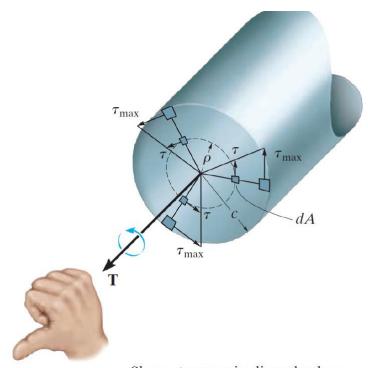
Shear stress varies linearly along each radial line of the cross section.

THE TORSION FORMULA

$$T = \frac{\tau_{\text{max}}}{c} \int_{A} \rho^2 \ dA$$

$$\tau_{\max} = \frac{\mathit{Tc}}{\mathit{J}}$$

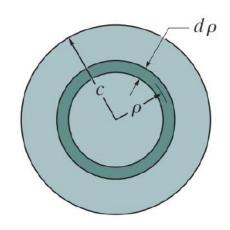
$$\tau = \frac{T\rho}{J}$$



Polar Moment of Inertia.

$$J = \int_{A} \rho^{2} dA = \int_{0}^{c} \rho^{2} (2\pi\rho d\rho)$$
$$= 2\pi \int_{0}^{c} \rho^{3} d\rho = 2\pi \left(\frac{1}{4}\right) \rho^{4} \Big|_{0}^{c}$$
$$J = \frac{\pi}{2} c^{4}$$

 $\tau = \frac{T\rho}{J}$

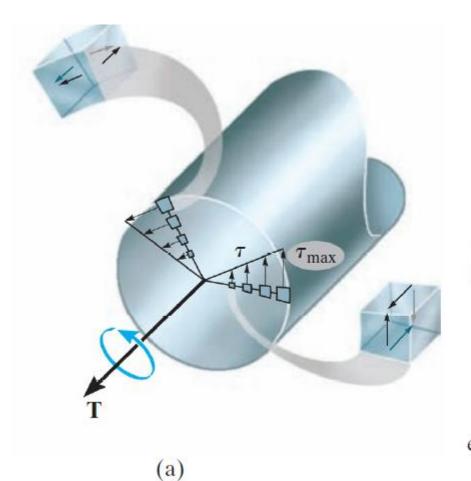


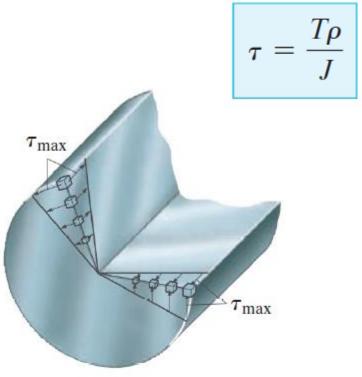
Solid Section

Note that J is always positive. Common units used for its measurement are mm^4 or in^4 .

$$J = \frac{\pi}{2} \left(c_o^4 - c_i^4 \right)$$

Shear Stress Distribution

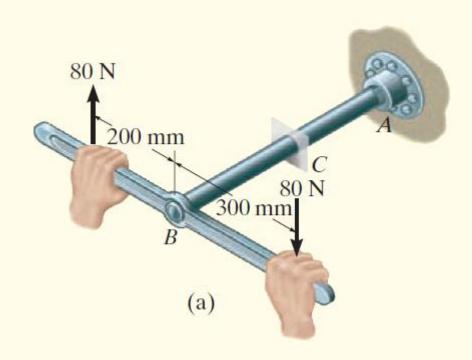




Shear stress varies linearly along each radial line of the cross section.

(b)

The pipe shown in Fig. 5–10a has an inner radius of 40 mm and an outer radius of 50 mm. If its end is tightened against the support at A using the torque wrench, determine the shear stress developed in the material at the inner and outer walls along the central portion of the pipe.

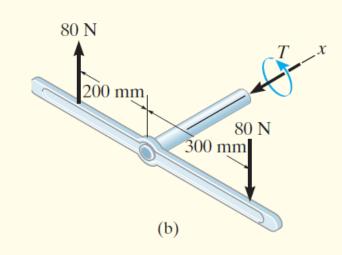


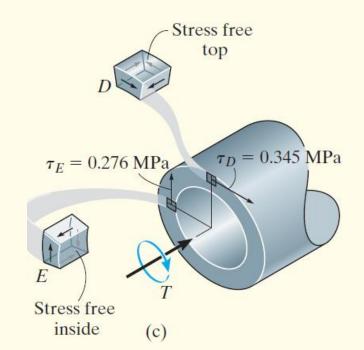
فصل چهارم: پیچش

Internal Torque.

Section Property.

Shear Stress.





POWER TRANSMISSION

Power is defined as the work performed per unit of time.

$$P = \frac{T d\theta}{dt}$$



Since the shaft's angular velocity is $\omega = d\theta/dt$, then the power is

$$P = T\omega$$

$$P = T\omega$$

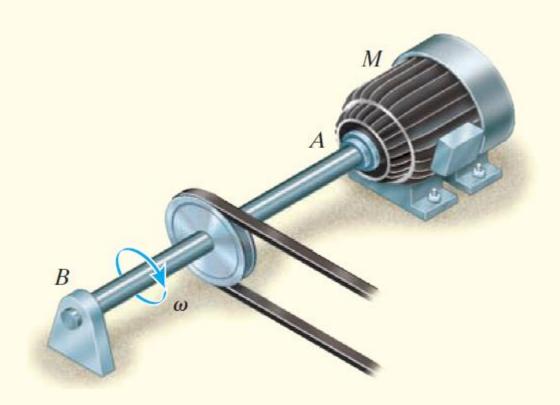
In the SI system, power is expressed in *watts* when torque is measured in newton-meters $(N \cdot m)$ and ω is in radians per second (rad/s) $(1 W = 1 N \cdot m/s)$. In the FPS system, the basic units of power are foot-pounds per second $(ft \cdot lb/s)$; however, *horsepower* (hp) is often used in engineering practice, where

$$1 \text{ hp} = 550 \text{ ft} \cdot \text{lb/s}$$

For machinery, the *frequency* of a shaft's rotation, f, is often reported. This is a measure of the number of revolutions or "cycles" the shaft makes per second and is expressed in hertz (1 Hz = 1 cycle/s). Since 1 cycle = 2π rad, then $\omega = 2\pi f$, and so the above equation for power can also be written as

$$P = 2\pi fT$$

A solid steel shaft AB, shown in Fig. 5–11, is to be used to transmit 5 hp from the motor M to which it is attached. If the shaft rotates at $\omega = 175$ rpm and the steel has an allowable shear stress of $\tau_{\rm allow} = 14.5$ ksi, determine the required diameter of the shaft to the nearest $\frac{1}{8}$ in.



فصل چهارم: پیچش

فصل چهارم : پیچش

ANGLE OF TWIST

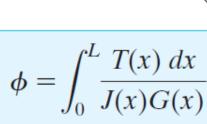
$$d\phi = \gamma \frac{dx}{\rho}, \gamma = \frac{d\phi}{dx} \rho$$

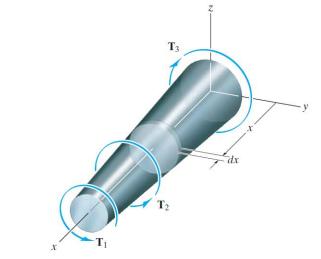
$$C = YG$$
, $C = \frac{T(x) f}{J(x)}$

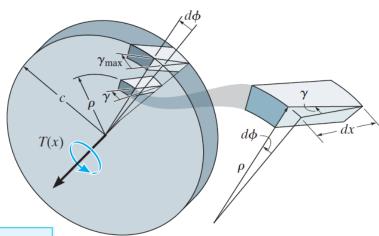
$$\frac{T(x) \beta}{J(x)} = YG = \frac{d\varphi}{dx} \beta G$$

$$\frac{T(x)}{J(x)} = \frac{d\varphi}{dx} G$$

$$d\phi = \frac{T(x)}{J(x)G(x)}dx \qquad \phi = \int_0^L \frac{T(x) dx}{J(x)G(x)}$$







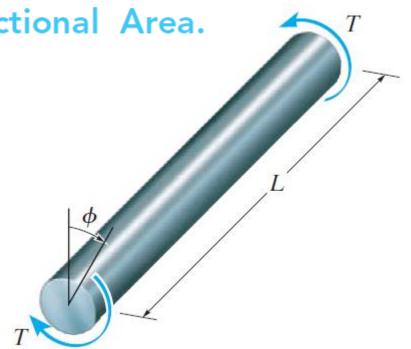
ANGLE OF TWIST

Constant Torque and Cross-Sectional Area.

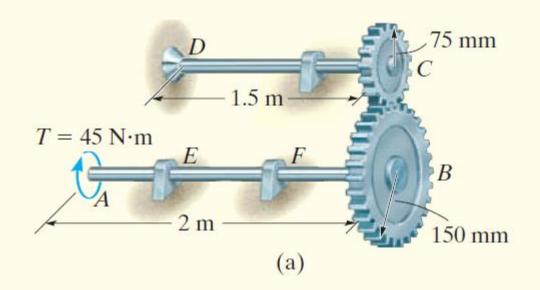
$$\phi = \frac{TL}{JG}$$

Multiple Torques.

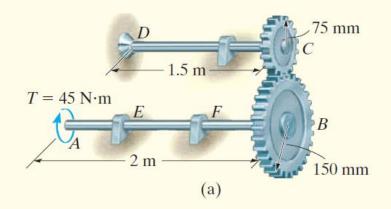
$$\phi = \sum \frac{TL}{JG}$$



The two solid steel shafts shown in Fig. 5–18a are coupled together using the meshed gears. Determine the angle of twist of end A of shaft AB when the torque $T=45~\mathrm{N}\cdot\mathrm{m}$ is applied. Shaft DC is fixed at D. Each shaft has a diameter of 20 mm. $G=80~\mathrm{GPa}$.

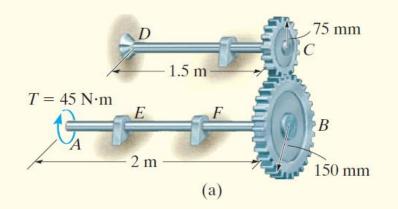


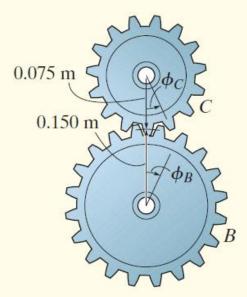
Internal Torque.



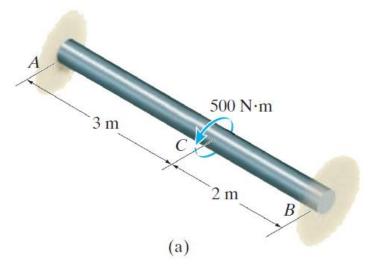
فصل چهارم: پیچش

Angle of Twist.





STATICALLY INDETERMINATE TORQUE-LOADED MEMBERS



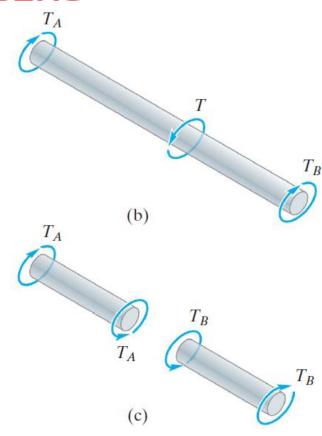
$$\Sigma M = 0;$$

$$500 \text{ N} \cdot \text{m} - T_A - T_B = 0$$

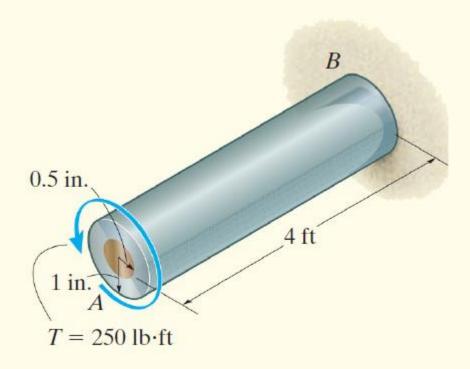
$$\phi_{A/B} = 0$$

$$\frac{T_A(3 \text{ m})}{JG} - \frac{T_B(2 \text{ m})}{JG} = 0 \qquad T_A = 200 \text{ N} \cdot \text{m} \quad \text{and} \quad T_B = 300 \text{ N} \cdot \text{m}$$

$$T_A = 200 \,\mathrm{N} \cdot \mathrm{m}$$

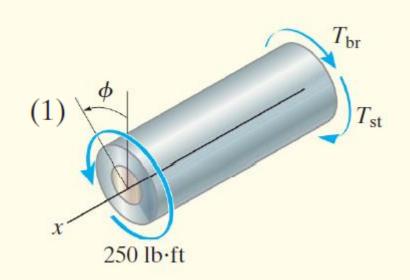


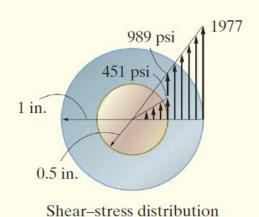
The shaft shown in Fig. 5–22*a* is made from a steel tube, which is bonded to a brass core. If a torque of $T = 250 \text{ lb} \cdot \text{ft}$ is applied at its end, plot the shear-stress distribution along a radial line on its cross section. Take $G_{\text{st}} = 11.4(10^3) \text{ ksi}$, $G_{\text{br}} = 5.20(10^3) \text{ ksi}$.



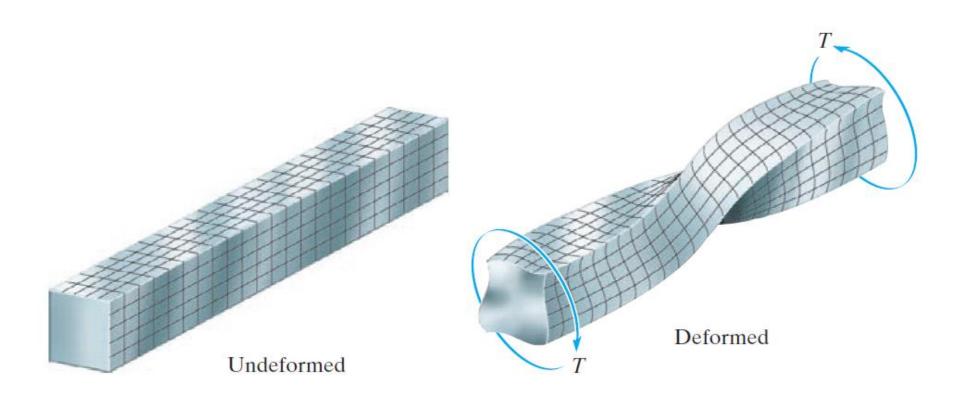
Equilibrium.

Compatibility.

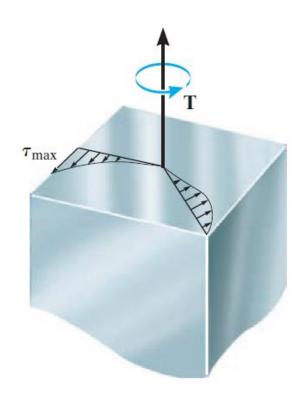




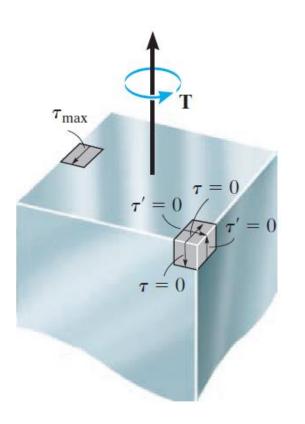
SOLID NONCIRCULAR SHAFTS



SOLID NONCIRCULAR SHAFTS

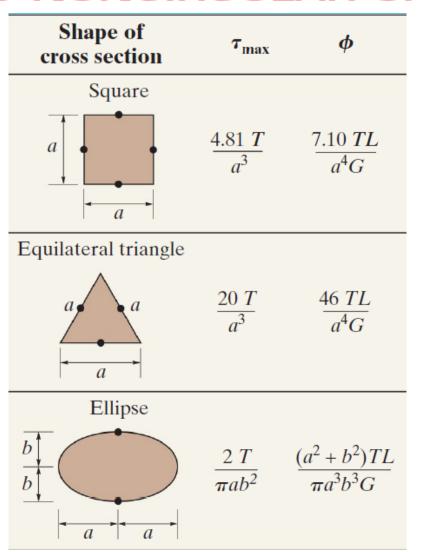


Shear stress distribution along two radial lines

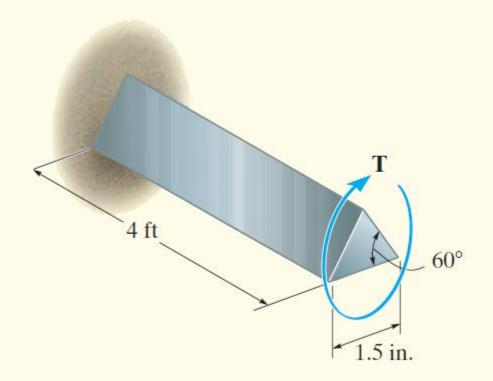


Warping of cross-sectional area

SOLID NONCIRCULAR SHAFTS



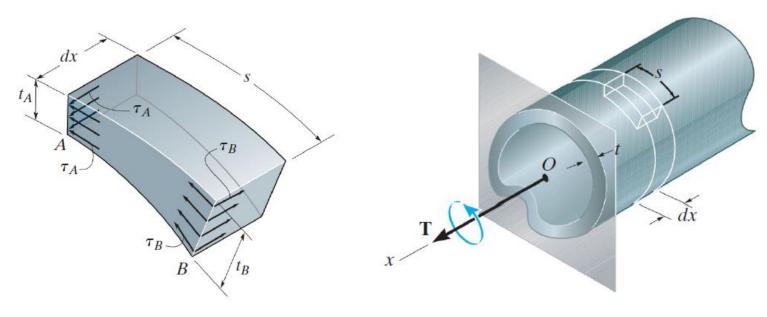
The 6061-T6 aluminum shaft shown in Fig. 5–25 has a cross-sectional area in the shape of an equilateral triangle. Determine the largest torque **T** that can be applied to the end of the shaft if the allowable shear stress is $\tau_{\text{allow}} = 8$ ksi and the angle of twist at its end is restricted to $\phi_{\text{allow}} = 0.02$ rad. How much torque can be applied to a shaft of circular cross section made from the same amount of material?



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فصل چهارم: پیچش

THIN-WALLED TUBES HAVING CLOSED CROSS SECTIONS



$$dF_A = \tau_A (t_A dx)$$

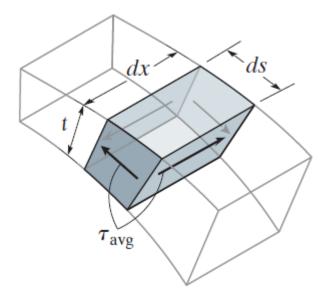
$$dF_B = \tau_B (t_B dx)$$

$$\tau_A t_A = \tau_B t_B$$

Shear Flow.

$$q = \tau_{\rm avg} t$$

dA = t ds, so that $dF = \tau_{avg}(t ds) = q ds$. q = dF/ds.

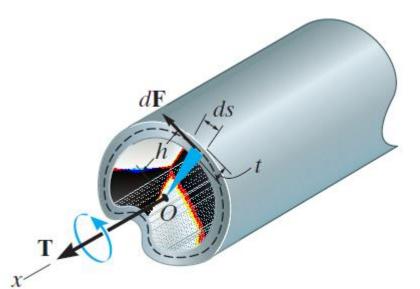


$$dF = \tau_{\text{avg}} dA = \tau_{\text{avg}} (t \, ds)$$

$$dT = h(dF) = h(\tau_{\text{avg}} t \, ds)$$

$$T = \oint h\tau_{\text{avg}} t \, ds$$

 $q = \tau_{\text{avg}} t$ is constant



فصل چهارم : پیچش

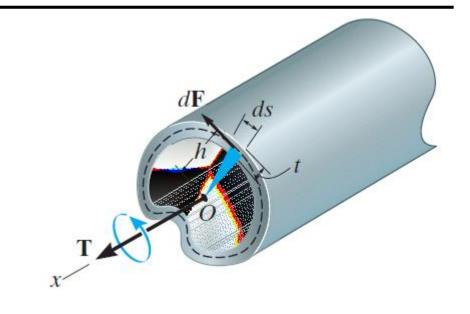
$$dF = \tau_{\text{avg}} dA = \tau_{\text{avg}} (t \, ds)$$

$$dT = h(dF) = h(\tau_{\text{avg}} t \, ds)$$

$$T = \oint h \tau_{\text{avg}} t \, ds$$

$$q = \tau_{\text{avg}} t \text{ is } constant$$

$$T = \tau_{\text{avg}} t \oint h \, ds$$



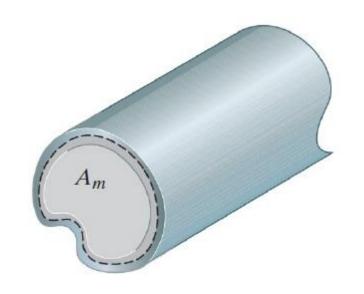
A graphical simplification can be made for evaluating the integral by noting that the *mean area*, shown by the blue colored triangle in Fig. 5–26d, is $dA_m = (1/2)h \, ds$. Thus,

$$T = 2\tau_{\text{avg}} t \int dA_m = 2\tau_{\text{avg}} t A_m$$

$$T = 2\tau_{\rm avg} t \int dA_m = 2\tau_{\rm avg} t A_m$$

$$\tau_{\text{avg}} = \frac{T}{2tA_m} \qquad q = \frac{T}{2A_m}$$

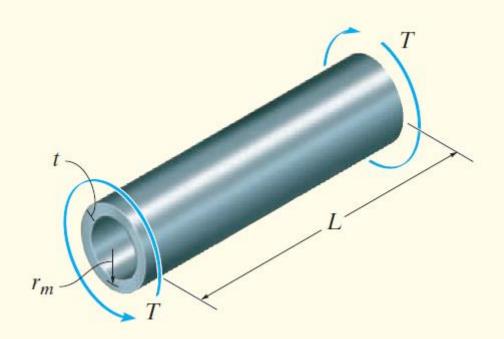
$$q = \frac{T}{2A_m}$$



Angle of Twist.
$$\phi = \frac{TL}{4A_m^2 G} \oint \frac{ds}{t}$$

Here again the integration must be performed around the entire boundary of the tube's cross-sectional area.

Calculate the average shear stress in a thin-walled tube having a circular cross section of mean radius r_m and thickness t, which is subjected to a torque T, Fig. 5–27a. Also, what is the relative angle of twist if the tube has a length L?



فصل چهارم: پیچش

Average Shear Stress. The mean area for the tube is $A_m = \pi r_m^2$. Applying Eq. 5–18 gives

$$\tau_{\text{avg}} = \frac{T}{2tA_m} = \frac{T}{2\pi t r_m^2}$$

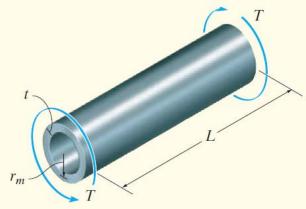
Ans.

We can check the validity of this result by applying the torsion formula. Here

$$J = \frac{\pi}{2} (r_o^4 - r_i^4)$$

$$= \frac{\pi}{2} (r_o^2 + r_i^2) (r_o^2 - r_i^2)$$

$$= \frac{\pi}{2} (r_o^2 + r_i^2) (r_o + r_i) (r_o - r_i)$$



Since
$$r_m \approx r_o \approx r_i$$
 and $t = r_o - r_i$, $J = \frac{\pi}{2} (2r_m^2) (2r_m)t = 2\pi r_m^3 t$

$$\tau_{\text{avg}} = \frac{Tr_m}{J} = \frac{Tr_m}{2\pi r_m^3 t} = \frac{T}{2\pi t r_m^2}$$

Ans.

Angle of Twist. Applying Eq. 5–20, we have

$$\phi = \frac{TL}{4A_m^2G} \oint \frac{ds}{t} = \frac{TL}{4(\pi r_m^2)^2 Gt} \oint ds$$

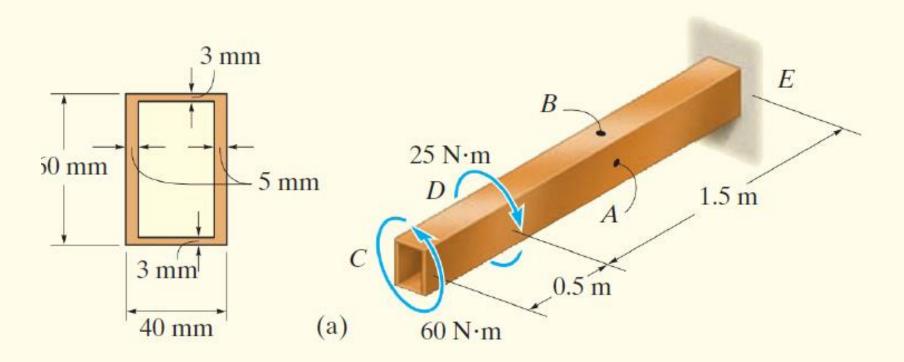
Actual shear-stress distribution (torsion formula) $\tau_{\rm avg}$ $au_{ ext{max}}$ au_{avg} Average shear-stress distribution (thin-wall approximation)

The integral represents the length around the centerline boundary, which is $2\pi r_m$. Substituting, the final result is

$$\phi = \frac{TL}{2\pi r_m^3 Gt}$$

Ans.

The tube is made of C86100 bronze and has a rectangular cross section as shown in Fig. 5–28a. If it is subjected to the two torques, determine the average shear stress in the tube at points A and B. Also, what is the angle of twist of end C? The tube is fixed at E.

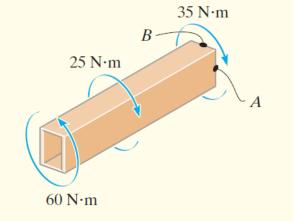


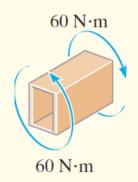
فصل چهارم: پیچش

TORSION

Angle of Twist. From the free-body diagrams in Fig. 5–28b and 5–28c, the internal torques in regions DE and CD are 35 N·m and 60 N·m, respectively. Following the sign convention outlined in Sec. 5.4, these torques are both positive. Thus, Eq. 5–20 becomes

$$\phi = \sum \frac{TL}{4A_m^2 G} \oint \frac{ds}{t}$$

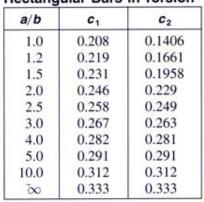


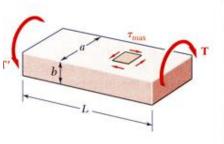


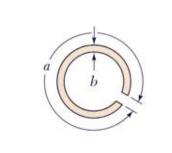
THIN-WALLED TUBES HAVING OPENED CROSS SECTIONS











For uniform rectangular cross-sections,

$$\tau_{\text{max}} = \frac{T}{c_1 a b^2} \qquad \phi = \frac{TL}{c_2 a b^3 G}$$

 At large values of a/b, the maximum shear stress and angle of twist for other open sections are the same as a rectangular bar.